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plant~~ Getting Started with
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2014 v2

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tests and in class* ~~PASSING
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HIL Simulation ~~Cómo modelar~~

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~~una planta y hacer un
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Pendulum Control with SimMechanics and QUARC How to Implement Quanser Interactive Labs in a Lecture - Demo

Rotary Inverted Pendulum

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With the SRV02 Base Unit, you can select from 10 add-on modules to create experiments of varying complexity across a wide range of topics, disciplines and courses. All of the experiments/workstations are

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**SRV02 Rotary Pendulum User
Manual - Engineering
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Instructor Manual 0 1 2 3.
The load attached to the
motor shaft includes a
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gears, and a single 120-tooth
gear along with any other
external load that is attached**

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to the load shaft.

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transfer function is $P_s(s) =$
 $\Theta_l(s) V_m(s)$. T The 1DBB
transfer function describes
the displacement of the ball
with respect to the load angle

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of the servo.

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(Furuta pendulum) module for**

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Rotary arm length: 21.6 cm:
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Simulink model are designed
to send a voltage to the
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SRV02 Rotary Pendulum User

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The load attached to the
motor shaft includes a
24-tooth gear, two 72-tooth**

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gears, and a single 120-tooth gear along with any other external load that is attached to the load shaft.

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transfer function describes the displacement of the ball with respect to the load angle of the servo.

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Product Details Specifications
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Rotary arm mass: 0.257 kg:
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Quanser SRV02 system. Using
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to send a voltage to the SRV02, read the load gear angle using a potentiometer and an encoder, and measured the speed of the load shaft using the tachometer.

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